

## Translation of original operating instruction

### V1 MCU-01X UP



## 1 General information

### 1.1 Notice

This document is part of the product. Keep this operating instruction for future references.

### 1.2 Scope of delivery

Check the delivery according to the delivery note.

#### Product designation

Art.-Nr.	Description
0108014	MCU-01X UP (incl. bus connector)
	Operating instruction

### 1.3 Product description

The motor control units are designed for the potential free control of 230 V<sub>AC</sub> drives with 2 end switches for blinds, awnings, large louvre blades, roller shutters, windows, light domes, etc. in a KNX bus system.

The module has 1 motor output and inputs for the connection of 2 conventional blind switches or 4 potential-free contacts.

The channel can be controlled individually via the KNX bus and operating states, position and fault messages for the connected drives/ blinds can be transmitted.

### 1.4 Limitations of liability

All information and notes in this operating instruction has been compiled in consideration of the applicable standards and regulations, the state of the art as well as our many years of knowledge and experience.

The manufacturer assumes no liability for damages and operational malfunction due to

- disregarding this operating instruction
- improper use
- faulty connection
- non-use of original spare parts and accessories

### 1.5 Disposal

The disposal of this product in normal household waste is forbidden within the European Union.

Dispose of the device via the municipal collection points.

The packaging materials used are recyclable. Dispose of packaging materials that are no longer required according to local regulations.

### 1.6 Copyright

This documentation is protected by copyright.

All rights reserved, including those of photomechanical reproduction, copying and distribution by means of special procedures (e.g. data processing, data carriers, and data networks), even in parts. Subject to technical changes and alterations in content.

### 1.7 Manufacturer/ Customer service

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## 2 Safety

### 2.1 Intended use

The motor control units are intended to control drives for blinds, awnings, large louvre blades, roller shutters, windows, light domes, etc. within the specified limits.

Any other use or extended use is considered to be improper.

### 2.2 Foreseeable misuse

Any use for a purpose other than the above mentioned purpose is improper. The risk of improper use or misuse is borne solely by the operator.

All types of claims due to damage arising from improper use are excluded.

### 2.3 Personnel's qualification


Improper use can cause considerable personal injury and material damage!


All tasks for installation, connection and commissioning must be carried out exclusively by a qualified electrician.

A qualified electrician is able to carry out work on electrical installations due to her/ his professional training, knowledge, and experience as well as knowledge of the relevant standards and regulations. She/ he can identify and avoid possible dangers.




The qualified electrician is trained for the specific place of employment in which she/ he is working and is aware of the relevant standards and regulations.

### 2.4 Basic safety instructions

	<b>⚠ DANGER</b>
	<b>Danger of life!</b> There is a risk of life when touching live parts. ▶ All tasks must be carried out exclusively by qualified personnel. ▶ Disconnect all power supplies before starting work.

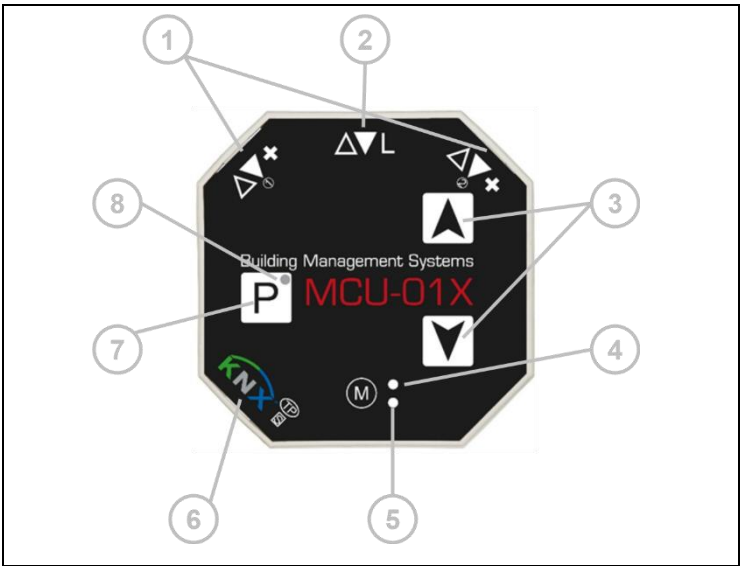
	<b>CAUTION</b>
	<b>Material damage!</b> Incorrect wiring and configuration of the device can lead to damage up to total failure. ▶ Ensure that the supply voltage corresponds to the specifications from the technical data for the device. ▶ Ensure that all external devices like push buttons and motors are connected correctly according to the wiring diagrams. ▶ Refer to technical documentation of the motor manufacturer for notes on required settings such as relais switching times. ▶ Refer to the software-helpfile for details on the configuration.

### 2.5 Signage

Symbol	Meaning
	General warning
	Electrostatic discharge
	CE label

## 3 Design and function

### 3.1 Complete overview



#### Location of control and display elements

- 1 Push button local operation (UP/ DOWN/ +)
- 2 Motor connection terminals
- 3 Test buttons (UP/ DOWN)
- 4 Status display motor output (red)
- 5 Status display motor output (green)
- 6 KNX bus connector
- 7 Programming button
- 8 Programming LED

### 3.2 Control and display elements

#### Programming button

- activates/ deactivates the programming mode (KNX bus voltage must be available)
- additionally, the programming button can be used to reset the device (for further information see chapter [troubleshooting](#))

#### Programming LED

- lights continuously "RED" when the programming mode is activated

#### Test buttons UP / DOWN

- to control the motor output in test mode
- short key press (< 0,4s) > step/ stop
- long key press (> 0,4s) > movement command end position
- additionally, the test buttons UP/DOWN can be used to re-learn the motor runtimes (for further information see chapter [troubleshooting](#))

### Status display motor output

- LED off = channel is in normal-/ automatic mode
- LED flashes "GREEN" = automatic lock is active (for further information see software-helpfile)
- LED lights continuously "GREEN" = channel is in test mode/ control via test buttons is activated
- LED flashes "RED" = security lock is active (for further information see software-helpfile)
- LED lights continuously "RED" > motor error (for further information see chapter [troubleshooting](#))

### 3.3 Local operation

The local operation can be installed as push button or switch.

If no adjustments have been made in the ETS configuration, the functionality is according to the following table

Function	Control
"Upper end position"	• long key press "UP" (> 0.4s)
"Lower end position"	• long key press "DOWN" (> 0.4s)
"Shading position"	• long key press "DOWN" (> 0.4s) immediately followed by • short key press "DOWN" (< 0.4s)
"STOP"	• short key press in opposite direction of current movement (< 0.4s)
"Move slats"	• short key press when stationary (< 0.4s)

## 4 Installation

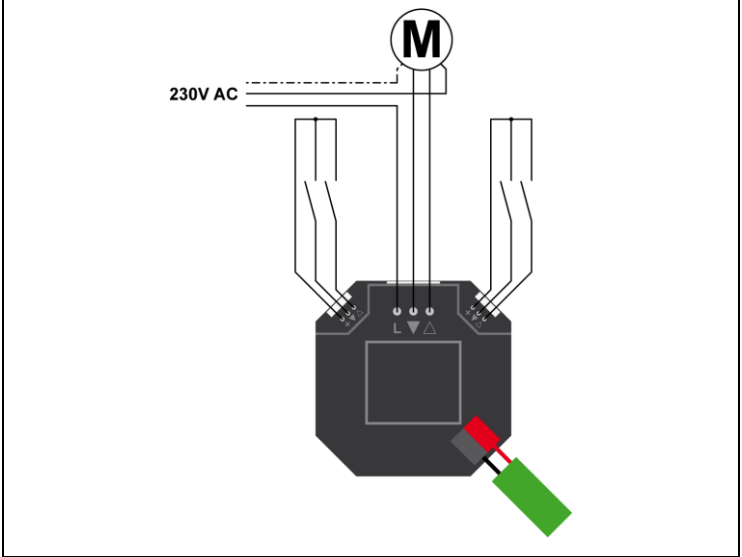
### 4.1 Mounting

To mount the device, proceed as follows

- connect all wirings
- place the device into the flush-mounted switch box
- mount buttons, switches, blanking covers or similar in front of the device

4.2 Electrical connection

Overview



Wiring diagram

Motor

Connect motors as follows

Motor connection terminals	Destination
△ / ▼	"UP / DOWN" Motor

NOTICE

If the direction of rotation is incorrect (test via test buttons) adjust the motor connection.

KNX-Bus

Connect the KNX bus connector to the KNX bus.

Supply voltage

Connect supply voltage to the motor control unit as follows

Power	
L	Phase 230V <sub>AC</sub>

Local operation

Several push buttons can be connected to one local operation input.

NOTICE

It is possible to connect one push button to several local operation inputs.  
This push button may only be connected within a device.

Local operation inputs	Destination
△	Push button "UP"
▼	Push button "DOWN"
+	Push button

4.3 Configuration

The configuration of the motor control unit is done via ETS from version 4.0 of KNX-Association.

NOTICE

For details about the configuration software see documentation of KNX-Association.

Requirements

- KNX bus voltage must be present

Approach

- ➡ connect PC/Laptop to the KNX bus via programming interface
- ➡ set the motor control unit to programming mode by pushing the programming button
- ↔ the programming LED lights continuously "RED"
- ➡ download the physical address and the application program

4.4 Commissioning/ Test run

For commissioning of the motor control unit proceed as follows

- check the condition of the device and the tight attachment of the terminals and connections
- turn on supply voltage
- check voltage and status LEDs on device
- check function and direction of rotation by means of test buttons – if the direction of rotation, is incorrect adjust the motor connection
- check the local operation – if the function is reversed, correct the local operation connection
- move blinds, awnings, large louvre blades, roller shutters, windows, light domes, etc. into a safe end position
- mount all protective covers
- maintain system documentation and, if necessary, affix labels and/ or signs

5 Operation

5.1 Manual operation

The manual operation is done via the local operation inputs of the motor control unit by means of push buttons or switches (see chapter [local operation](#)) and/ or via the KNX system (see software-helpfile).

5.2 Automatic operation

Automatic operation is performed according to the parameters specified in the ETS configuration. The control commands received via the KNX bus are considered.

6 Troubleshooting

NOTICE

If the listed troubleshooting procedures do not lead to the desired result, contact the customer service.

Fault	Rectification
motor error status LED for the corresponding motor lights continuously "RED"	<ul style="list-style-type: none"><li>• check motor connection, motor cable, and motor</li></ul>
device does not communicate via KNX	<ul style="list-style-type: none"><li>• check KNX bus voltage (programming LED can be switched on and off via the programming button)</li></ul>

Fault	Rectification
no local/ manual commands are executed	<ul style="list-style-type: none"><li>• check whether a security lock is active (status LED for the output flashes "RED") – the triggering and reset conditions for a security lock are defined in the ETS configuration by the system integrator</li><li>• check local operation inputs and/ or KNX communication</li></ul>
no central/ automatic commands are executed	<ul style="list-style-type: none"><li>• check whether a security lock is active (status LED for the output flashes "RED") – the triggering and reset conditions for a security lock are defined in the ETS configuration by the system integrator</li><li>• check whether an automatic lock is active (status LED for the output flashes "GREEN") – the triggering and reset conditions for an automatic lock are defined in the ETS configuration by the system integrator</li><li>• check KNX communication</li></ul>

Re-learn motor runtimes

If runtimes have been learned incorrectly or if the runtimes have changed considerably (e.g. by a motor change), the stored runtimes can be deleted and re-learned.

- ➡ press test buttons "UP" and "DOWN" simultaneously for at least 5s
- ↔ the runtimes will be re-learned during the next position movement

Reset the device to the factory setting

A reset must be carried out for resetting the device to the factory setting.

NOTICE

The reset will clear the entire configuration.

- ➡ press programming button for at least 10s (all status displays of the motor outputs flash)
- ➡ press programming button again within 10s and keep it pressed for at least 10 more seconds (status LED of the motor output lights continuously "RED")
- ➡ press programming button again within 10s and keep it pressed for at least 10 more seconds (the device is reset to factory settings)
- ↔ the restart of the device is shown by flashing the status LEDs of inputs and motor outputs

7 Technical data

General		
Operating environment	Dry rooms (free of condensation) +5° to +45°C pollution index 2	
Mounting	in flush-mounted switch box	
Dimensions (W x H x D)	51 x 51 x 27	mm
Weight	50	g
Binary inputs	4	
Motor outputs	1	

NOTICE

The connection and the wiring of the local operation units and the KNX bus must be carried out according to the current SELV requirements.

Connection data	
Supply voltage	via KNX
Electrical protection	IP 20
Electrical protection class	II

Motor connection (Outputs)		
Motor type	230	V <sub>AC</sub>
	max. 2.5	A
	2 end switches	
Cable	3 wires	
	single or fine wire	
Wire cross-section	0,5 – 1,5	mm <sup>2</sup>

Local operation (Inputs)		
Voltage	20	V <sub>DC</sub>
Current	2	mA
Cable	3 wires	
	Single or fine wire	
Wire cross-section	0,14 – 0,34	mm <sup>2</sup>
Cable length max.	100	m
Operation via	Push button or switch potential-free contact	

KNX		
Bus connector	Ø 0.5 ... 0.8	mm
	single wire	
Bus cable	according to KNX standard	