Building Management Systems

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Translation of original operating instruction V2 MCU-16 SMI AC V2 MCU-16 SMI LoVo





I General information

1.1 Notice

This document is part of the product. Keep this operating instruction for future references.

1.2 Scope of delivery

Check the delivery according to the delivery note.

Product designation

ArtNr.	Description
0108016	V2 MCU-16 SMI AC actuator for 230V SMI drives
0108017	V2 MCU-16 SMI LoVo actuator for 24V DC SMI drives
	Operating instruction

1.3 Product description

The motor control units are designed for the control of 230 V_{AC} and 24V LoVo drives with SMI interface for blinds, awnings, large louvre blades, roller shutters, windows, light domes, etc. in a KNX bus system.

Each device has 4 lines and inputs for the connection of 4 conventional blind switches or 8 potential-free contacts. A total of 16 SMI drives can be connected in any order to the 4 lines.

Each channel or motor can be controlled individually via the KNX bus and operating states, position and fault messages for the connected drives/blinds can be transmitted.

Communication takes place according to the SMI standard 3.0 BF.

1.4 Limitations of liability

All information and notes in this operating instruction has been compiled in consideration of the applicable standards and regulations, the state of the art as well as our many years of knowledge and experience.

The manufacturer assumes no liability for damages and operational malfunction due to

- disregarding this operating instruction
- improper use
- faulty connection
- non-use of original spare parts and accessories

1.5 Disposal

The disposal of this product in normal household waste is forbidden within the European Union.

Dispose of the device via the municipal collection points.

The packaging materials used are recyclable. Dispose of packaging materials that are no longer required according to local regulations.

1.6 Copyright

This documentation is protected by copyright.

All rights reserved, including those of photomechanical reproduction, copying and distribution by means of special procedures (e.g. data processing, data carriers, and data networks), even in parts. Subject to technical changes and alterations in content.

1.7 Manufacturer/ Customer service

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2 Safety

2.1 Intended use

The motor control units are intended to control drives for blinds, awnings, large louvre blades, roller shutters, windows, light domes, etc. within the specified limits.

Any other use or extended use is considered to be improper.

2.2 Foreseeable misuse

Any use for a purpose other than the above mentioned purpose is improper. The risk of improper use or misuse is borne solely by the operator.

All types of claims due to damage arising from improper use are excluded.

2.3 Personnel's qualification

Improper use can cause considerable personal injury and material damage! All tasks for installation, connection and commissioning must be carried out exclusively by a qualified electrician.

A qualified electrician is able to carry out work on electrical installations due to her/ his professional training, knowledge, and experience as well as knowledge of the relevant standards and regulations. She/ he can identify and avoid possible dangers.

The qualified electrician is trained for the specific place of employment in which she/ he is working and is aware of the relevant standards and regulations.

2.4 Basic safety instructions



Danger of life!

There is a risk of life when touching live parts.

► All tasks must be carried out exclusively by qualified person-

△DANGER

Disconnect all power supplies before starting work.



Material damage!

Incorrect wiring and configuration of the device can lead to damage up to total failure.

▶ Ensure that the supply voltage corresponds to the specifications from the technical data for the device.

CAUTION

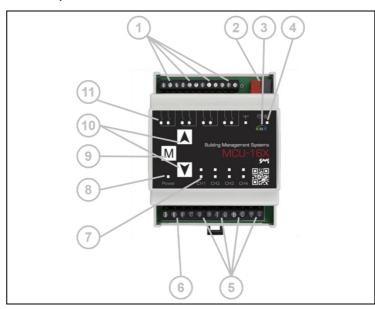
- Ensure that all external devices like push buttons and motors are connected correctly according to the wiring diagrams.
- ► Refer to technical documentation of the motor manufacturer for notes on required settings.
- Refer to the software-helpfile for details on the configuration.

2.5 Signage

Symbol	Meaning
<u>•</u>	General warning
≪	Electrostatic discharge
CE	CE label

3 Design and function

3.1 Complete overview



Location of control and display elements

- 1 Push button local operation (UP/ DOWN/+)
- 2 KNX bus connector
- 3 Programming button
- 4 Programming LED
- 5 Motor connection terminals
- 6 Connection terminal supply voltage
- 7 Status display motor output
- 8 Status display Power
- 9 Test button M
- 10 Test buttons (UP/ DOWN)
- 11 Status display local operation

3.2 Control and display elements

Status display Power

- lights continuously "GREEN" when the device is ready for operation
- flashes frequently, when Power is not connected properly

Programming button

 activates/ deactivates the programming mode (KNX bus voltage must be available)

Programming LED

- lights continuously "RED" when the programming mode is activated
- flashes if there is no bus voltage
- does not light, when KNX- communication is in ready mode

Test button M

 used to select a line for direct operation via the test buttons UP/ DOWN (test mode) –

if a line is in test mode, the corresponding status LED lights continuously "GREEN"

- by briefly pressing the M button all 4 channels are switched to the test mode
- each additional operation switches through the individual channels 1, 2, 3, 4
- after 6 operations all channels are in normal mode again
- additionally the M button can be used to reset the device (for further information see chapter troubleshooting)

Test buttons UP/ DOWN

- to control the motor outputs in test mode
- short key press (< 0,4s) > step/ stop
- long key press (> 0,4s) > movement command end position
- additionally the test buttons UP/ DOWN can be used to re-learn the motor addressing (for further information see chapter troubleshooting)

Status display motor output

- LED off = channel is in normal-/ automatic mode
- LED flashes "GREEN" = automatic lock is active (for further information see software-helpfile)
- LED lights continuously "GREEN" = channel is in test mode/ control via test buttons is activated
- LED flashes "RED" = security lock is active (for further information see software-helpfile)
- LED lights continuously "RED" > SMI line error (for further information see chapter troubleshooting)

Status display local operation

the corresponding LED (UP/ DOWN) lights "GREEN" as long as the button of the local operation is pressed

3.3 Local operation

The local operation can be installed as push button or switch.

If no adjustments have been made in the ETS configuration, the functionality is according to the following table

Function	Control
"Upper end positon"	• long key press "UP" (> 0.4s)
"Lower end position"	• long key press "DOWN" (> 0.4s)
"Shading position"	 long key press "DOWN" (> 0.4s) immediately followed by short key press "DOWN" (< 0.4s)
"STOP"	 short key press in opposite direction of current movement (< 0.4s)
"Move slats"	• short key press when stationary (< 0.4s)

4 Installation

4.1 Mounting

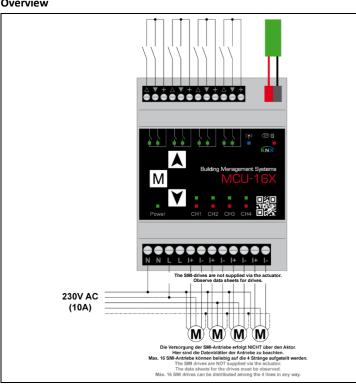
To mount the actuator proceed as follows

• place the module on the DIN rail in the desired position and lock in

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4.2 Electrical connection

Overview



Wiring diagram



The drives are not supplied via the actuator. The data sheets and information of the drives are to be considered. Mixed operation between AC and LoVo drives is not permitted.

Motor

Connect motors as follows

Motor connection terminals	Destination
I+ / I-	I+ und I- of SMI line
I+ / I-	I+ und I- of SMI line
I+ / I-	I+ und I- of SMI line
I+ / I-	I+ und I- of SMI line



NOTICE

Communication to the SMI drives only works properly when I+ and I- are connected correct.

KNX-Bus

Connect the KNX bus connector to the KNX bus.

Supply voltage

Connect supply voltage to the motor control unit as follows

Power	
L	Phase
N	Neutral conductor

Local operation

Several push buttons can be connected to one local operation input.

•	NOTICE
	It is possible to connect one push button to several local operation inputs. This push button may only be connected to one SMI actuator

Local operation inputs	Destination
Δ	Push button "UP"
▼	Push button "DOWN"
+	Push button

4.3 Configuration

The configuration of the motor control unit is done via ETS from version 5.0 of KNX-Association.



For details about the configuration software see documentation of KNX-Association.

Requirements

> supply voltage and KNX bus voltage must be present

- Connect PC/Laptop to the KNX bus via programming interface
- Set the motor control unit to programming mode by pushing the programming button
- address and the application program

4.4 Commissioning/ Test run

For commissioning of the motor control unit proceed as follows

- check the condition of the device and the tight attachment of the terminals and connections
- switch on the supply voltage
- check supply voltage and status LED Power on the device
- check function of the SMI drives by means of test buttons if communication to the SMI drives is not possible, check SMI wiring
- check the local operation -
- if the function is reversed, correct the local operation connection
- move blinds, awnings, large louvre blades, roller shutters, windows, light domes, etc. into a safe end position
- mount all protective covers
- maintain system documentation and, if necessary, affix labels and/ or signs

5 Operation

5.1 Manual operation

The manual operation is done via the local operation inputs of the motor control unit by means of push buttons or switches (see chapter local operation) and/ or via the KNX system (see software-helpfile).

5.2 Automatic operation

Automatic operation is performed according to the parameters specified in the ETS configuration. The control commands received via the KNX bus are

6 Troubleshooting



NOTICE

If the listed troubleshooting procedures do not lead to the desired result, contact the customer service.

Fault	Rectification
motor error status LED for the cor- responding motor lights continuously "RED"	check motor connection, motor cable, and motor
device does not com- municate via KNX	check KNX bus voltage (programming LED must not flash)

ault	Rectification		
no local/ manual com- nands are executed	check whether the corresponding output is in test mode (status LED for the output lights continuously "GREEN") — press the M key several times to exit the test mode (all status LEDs of the outputs do not light continuously "GREEN")		
	check whether a security lock is active (status LED for the output flashes "RED") – the triggering and reset conditions for a security lock are defined in the ETS configuration by the system integrator		
	check local operation inputs and/ or KNX communication		
no central/ automatic commands are exe- cuted	check whether the corresponding output is in test mode (status LED for the output lights continuously "GREEN") — press the M key several times to exit the test mode (all status LEDs of the outputs do not light continuously "GREEN") check whether a security lock is active (status LED for the output flashes "RED") — the triggering and reset conditions for a security lock are defined in the ETS configuration		
	by the system integrator • check whether an automatic lock is active (status LED for the output flashes "GREEN") –		
	the triggering and reset conditions for an au- tomatic lock are defined in the ETS configura- tion by the system integrator		
	check KNX communication		
a-learn motor addresse	s		

Re-learn motor addresses

If the motor addresses shall be re-learned (e.g. by a motor change), the stored addresses can be deleted and re-learned.

- switch motor output to test mode by pressing test button M (status LED) of the output is permanently "GREEN")
- press test buttons "UP" and "DOWN" simultaneously for at least 5s
- ⟨□ New motors get a new address this way.

Reset the device to the factory setting

A reset must be carried out for resetting the device to the factory setting.



The reset will clear the entire configuration.

- ⇒press test button M for at least 10s (all status LEDs of the motor outputs flash alternately "RED" and "GREEN")
- press test button M again within 10s and keep it pressed for at least 10 more seconds (all status LEDs of the motor outputs light continuously
- ⇒press test button M again within 10s and keep it pressed for at least 10 more seconds (the device is reset to factory settings)
- ⇔ the restart of the device is shown by flashing the status LEDs of inputs and motor outputs

Technical data

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General		
Operating environment	Dry rooms (free of condensation) +5° to +45°C pollution index 2	
Mounting	DIN rail 35mm or equivalent	
Dimensions	4 SU	
(W x H x D)	72 x 90.5 x 62	mm
Weight	200	g
Binary inputs	8	
Motor lines	4	
Number of motors	16 (free allocation to the 4 lines)	



NOTICE

The connection and the wiring of the local operation units and the KNX bus must be carried out according to the current SELV requirements.

Connection data		
Supply voltage	230 ± 10 %	V_{AC}
	50	Hz
Power consumption	<1	W
Cable	2 wires	
	single or fine wire	
Wire cross-section	2.5	mm²
Terminal tightening torque	0.4	Nm
Electrical protection	IP 20	
Electrical protection class	II	
·	·	·

Motor connection (Outputs)		
Motor type	SMI 230	V _{AC}
	SMI LoVo 24	V_{DC}
Cable	2 wires	
	single or fine wire	
Wire cross-section	2.5	mm²
Terminal tightening torque	0.4	Nm

Local operation (Inputs)		
Voltage	8	V_{DC}
Current	2	mA
Cable	3 wires	
	Single or fine wire	
Wire cross-section	1.5	mm²
Terminal tightening torque	0.25	Nm
Cable length max.	100	m
Operation via	Push button or switch potential-free contact	

KNX			
Bus connector	Ø 0.5 0.8	mm	
	single wire		
Bus cable	according to KNX standard		

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